

# DSC 140A

*Probabilistic Modeling & Machine Learning*

Lecture 14 | Part 1

**Bayes with Multiple Features**

# Recap

- ▶ **Bayes Classifier:** predict  $y$  that maximizes  $\mathbb{P}(Y = y | X = x)$

- ▶ **Alternatively:** predict  $y$  that maximizes

$$p_X(x | Y = y)\mathbb{P}(Y = y)$$

- ▶ We must estimate these probabilities/densities.

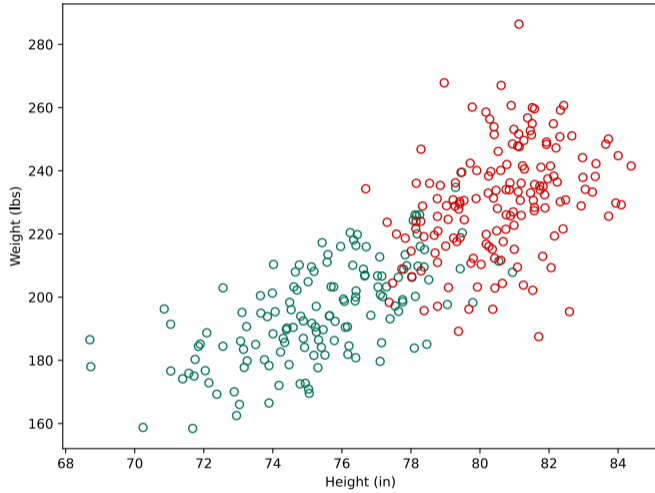
# Example: NBA Players

- ▶ **Guard** and **Forward** are two positions in basketball.
- ▶ Forwards tend to be larger than guards.



## Example: NBA Players

- ▶ Suppose we have a data set of  $n$  NBA players:
  - ▶  $X_1$ : the player's height
  - ▶  $X_2$ : the player's weight
  - ▶  $Y$ : the player's position (1 = guard, 0 = forward)
  
- ▶ **Given:** a new player's height and weight, predict their position.



# Bayes in $\geq 2$ Dimensions

- ▶ With one feature, Bayes said to pick  $y$  maximizing:

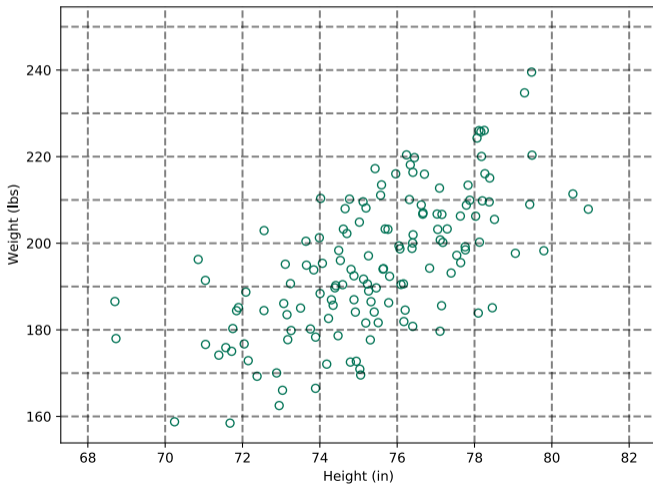
$$p_x(x | Y = y)\mathbb{P}(Y = y)$$

- ▶ With  $k$  features, pick  $y$  maximizing:

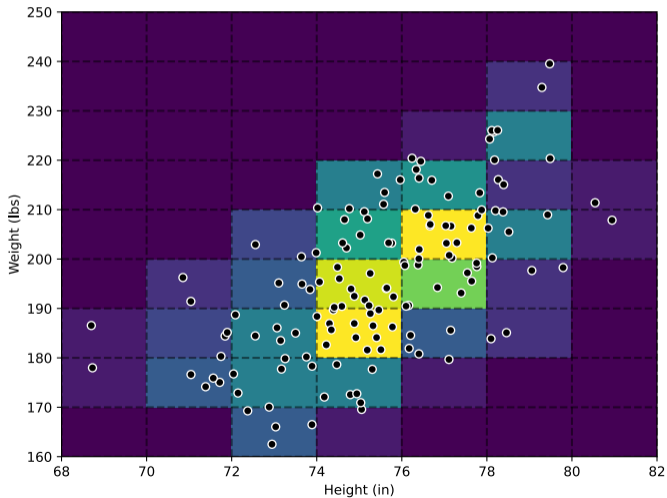
$$p_{\vec{x}}(\vec{x} | Y = y)\mathbb{P}(Y = y)$$

- ▶  $\vec{x}$  is the **feature vector**. Here: (height, weight)<sup>T</sup>
- ▶ We need to estimate density  $p(\vec{x} | Y = y)$  for each class.

# Estimating with Histograms

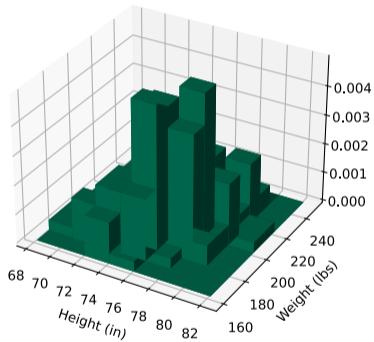


# Estimating with Histograms





# Estimating with Histograms



# Predicting with Histograms

To predict the class of an input  $\vec{x}$ :

1. Use histograms to estimate  $p_{\vec{x}}(\vec{x} | Y = y)$  for each class separately.
2. Predict the class  $y$  maximizing

$$p_{\vec{x}}(\vec{x} | Y = y) \mathbb{P}(Y = y)$$

# Histogram Estimators

- ▶ Histogram density estimators are very flexible.
- ▶ But suffer heavily from **curse of dimensionality**.
- ▶ Not feasible for estimating density in more than a few dimensions.

# Today

- ▶ **Last time:** we saw the **parametric** approach to density estimation.
  - ▶ Pick a parametric distribution (e.g., Gaussian)
  - ▶ Find parameters by maximizing likelihood
- ▶ We saw how to do this for one-dimensional data.
- ▶ **Today:** multidimensional data.

## In particular...

- ▶ **Today:** multivariate Gaussian density estimation.
- ▶ That is: fitting multivariate Gaussians to data with maximum likelihood.

# DSC 140A

*Probabilistic Modeling & Machine Learning*

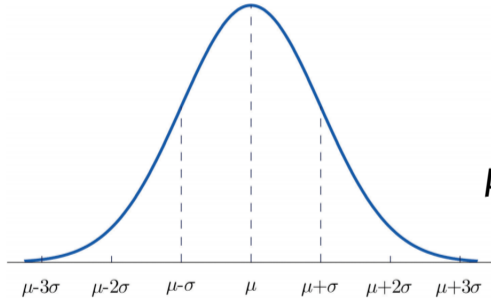
Lecture 14 | Part 2

**Multivariate Gaussians**

# Multivariate Gaussians

- ▶ In 1 dimension, a Gaussian seemed to describe distribution of heights.
- ▶ Does a **multivariate** Gaussian describe distribution of heights and weights?

# “Deriving” Multivariate Gaussians



$$X \sim \mathcal{N}(\mu, \sigma^2)$$

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}(x-\mu)^2/\sigma^2}$$



# Setting #1

- ▶ Suppose we have  $d$  independent random variables  $X_1, \dots, X_d$ .
- ▶ Assume that each is Gaussian; different mean, but **same** variance:

$$X_1 \sim \mathcal{N}(\mu_1, \sigma^2), \quad X_2 \sim \mathcal{N}(\mu_2, \sigma^2), \dots, \quad X_d \sim \mathcal{N}(\mu_d, \sigma^2).$$

$$P(A, B) = P(A) P(B)$$

## Setting #1

- ▶ What is the **joint density**  $p(x_1, x_2, \dots, x_d)$ ?
- ▶ Since we assumed  $X_1, \dots, X_d$  are independent:

$$\begin{aligned} p(x_1, x_2, \dots, x_d) &= p(x_1)p(x_2) \cdots p(x_d) \\ &= \left( \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}(x_1-\mu_1)^2/\sigma^2} \right) \cdot \left( \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}(x_2-\mu_2)^2/\sigma^2} \right) \cdots \left( \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}(x_d-\mu_d)^2/\sigma^2} \right) \end{aligned}$$

$$e^x e^y = e^{x+y}$$

## Setting #1

- ▶ What is the **joint density**  $p(x_1, x_2, \dots, x_d)$ ?
- ▶ Since we assumed  $X_1, \dots, X_d$  are independent:

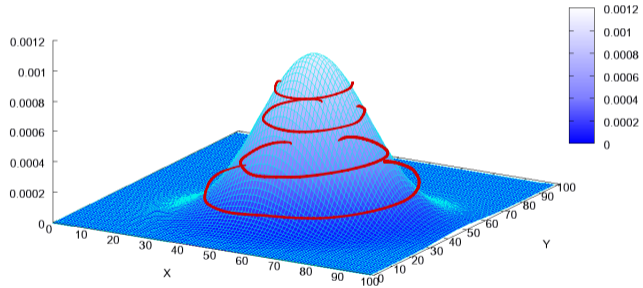
$$\begin{aligned} p(x_1, x_2, \dots, x_d) &= p(x_1)p(x_2) \cdots p(x_d) \\ &= \left( \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}(x_1-\mu_1)^2/\sigma^2} \right) \cdot \left( \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}(x_2-\mu_2)^2/\sigma^2} \right) \cdots \left( \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}(x_d-\mu_d)^2/\sigma^2} \right) \\ &= \frac{1}{(2\pi\sigma^2)^{d/2}} \exp\left(-\frac{(x_1-\mu_1)^2 + (x_2-\mu_2)^2 + \dots + (x_d-\mu_d)^2}{2\sigma^2}\right) \end{aligned}$$

# Setting #1

- ▶ What is the **joint density**  $p(x_1, x_2, \dots, x_d)$ ?
- ▶ Since we assumed  $X_1, \dots, X_d$  are independent:

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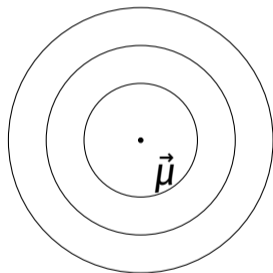
# Setting #1



# Setting #1: Spherical Gaussians

$$p(\vec{x}) = \frac{1}{(2\pi\sigma^2)^{d/2}} \exp\left(-\frac{1}{2} \frac{\|\vec{x} - \vec{\mu}\|^2}{\sigma^2}\right)$$

- ▶ Contours are (hyper)spheres.
- ▶ Every slice through middle gives same Gaussian.



## Setting #2

- ▶ Still assume  $X_1, \dots, X_d$  are independent, Gaussian.
- ▶ But they now have different variances:

$$X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2), \quad X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2), \dots, \quad X_d \sim \mathcal{N}(\mu_d, \sigma_d^2).$$

## Setting #2

$$\begin{aligned} p(x_1, x_2, \dots, x_d) &= p(x_1)p(x_2) \cdots p(x_d) \\ &= \left( \frac{1}{\sqrt{2\pi\sigma_1^2}} e^{-\frac{1}{2}(x_1-\mu_1)^2/\sigma_1^2} \right) \cdot \left( \frac{1}{\sqrt{2\pi\sigma_2^2}} e^{-\frac{1}{2}(x_2-\mu_2)^2/\sigma_2^2} \right) \cdots \left( \frac{1}{\sqrt{2\pi\sigma_d^2}} e^{-\frac{1}{2}(x_d-\mu_d)^2/\sigma_d^2} \right) \end{aligned}$$



## Setting #2

$$\begin{aligned} p(x_1, x_2, \dots, x_d) &= p(x_1)p(x_2) \cdots p(x_d) \\ &= \left( \frac{1}{\sqrt{2\pi\sigma_1^2}} e^{-\frac{1}{2}(x_1-\mu_1)^2/\sigma_1^2} \right) \cdot \left( \frac{1}{\sqrt{2\pi\sigma_2^2}} e^{-\frac{1}{2}(x_2-\mu_2)^2/\sigma_2^2} \right) \cdots \left( \frac{1}{\sqrt{2\pi\sigma_d^2}} e^{-\frac{1}{2}(x_d-\mu_d)^2/\sigma_d^2} \right) \\ &= \frac{1}{(2\pi)^{d/2} \sigma_1 \cdot \sigma_2 \cdots \sigma_d} \exp\left(-\frac{1}{2} \left[ \frac{(x_1 - \mu_1)^2}{\sigma_1^2} + \frac{(x_2 - \mu_2)^2}{\sigma_2^2} + \dots + \frac{(x_d - \mu_d)^2}{\sigma_d^2} \right]\right) \end{aligned}$$

## Setting #2

- ▶ Define

$$C = \begin{pmatrix} \sigma_1^2 & 0 & \dots & 0 \\ 0 & \sigma_2^2 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \sigma_d^2 \end{pmatrix} \quad C^{-1} = \begin{pmatrix} 1/\sigma_1^2 & & & \\ & 1/\sigma_2^2 & & \\ & & \dots & \\ & & & 1/\sigma_d^2 \end{pmatrix}$$

- ▶ Then:

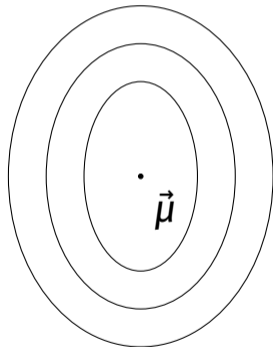
$$p(\vec{x}) = \frac{1}{(2\pi)^{d/2} |C|^{1/2}} \exp\left(-\frac{1}{2}(\vec{x} - \vec{\mu})^T C^{-1}(\vec{x} - \vec{\mu})\right)$$

where  $|C|$  is the **determinant** of  $C$ .

## Setting #2: **Axis-Aligned** Gaussians

$$p(\vec{x}) = \frac{1}{(2\pi)^{d/2} |\mathbf{C}|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(\vec{x} - \vec{\mu})^T \mathbf{C}^{-1}(\vec{x} - \vec{\mu})\right)$$

- ▶ Contours are axis-aligned (hyper)ellipses.
- ▶  $\mathbf{C}$  is the **covariance matrix**.
  - ▶ Diagonal.
  - ▶ Entries are variances.



## Setting #3: **General** Gaussians

- ▶ We have assumed that  $X_1, \dots, X_d$  are independent.
- ▶ Now assume that they're not. Define **covariance**:

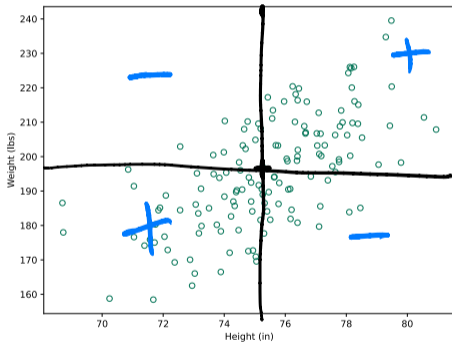
$$\text{Cov}(X_i, X_j) = \mathbb{E}[(X_i - \mu_i)(X_j - \mu_j)]$$

- ▶ **Note:**

$$\text{Var}(X_i) = \text{Cov}(X_i, X_i)$$

# Covariance

- ▶ Covariance measures how much two quantities **vary together**.



$$\text{Cov}(X_i, X_j) = \mathbb{E}[(X_i - \mu_i)(X_j - \mu_j)]$$

## Setting #3: General Gaussians

- ▶ Now the **covariance matrix** has off-diagonal elements:

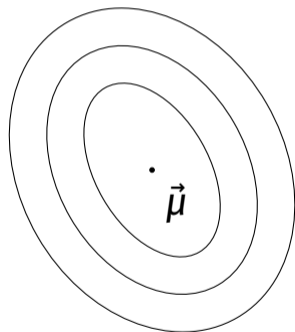
$$C = \begin{pmatrix} \text{Var}(X_1) & \text{Cov}(X_1, X_2) & \cdots & \text{Cov}(X_1, X_d) \\ \text{Cov}(X_2, X_1) & \text{Var}(X_2) & \cdots & \text{Cov}(X_2, X_d) \\ \cdots & \cdots & \cdots & \cdots \\ \text{Cov}(X_d, X_1) & \text{Cov}(X_d, X_2) & \cdots & \text{Var}(X_d) \end{pmatrix}$$

- ▶ Since  $\text{Cov}(X_i, X_j) = \text{Cov}(X_j, X_i)$ ,  $C$  is symmetric.

## Setting #3: **General** Gaussians

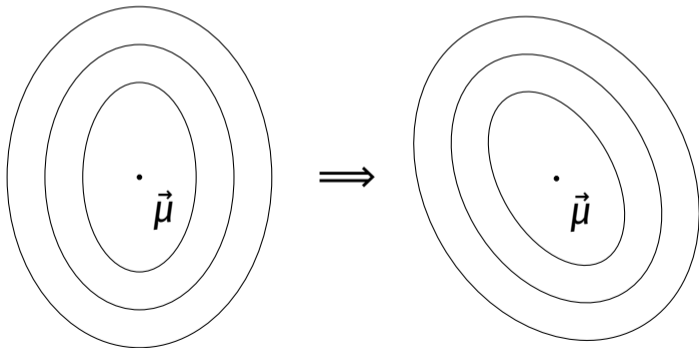
$$p(\vec{x}) = \frac{1}{(2\pi)^{d/2} |C|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(\vec{x} - \vec{\mu})^T C^{-1}(\vec{x} - \vec{\mu})\right)$$

Contours are general (hyper)ellipses.  
C need not be diagonal.



# General Gaussians: Another View

- ▶ A **general** Gaussian is an **axis-aligned** Gaussian that has been rotated:





# General Gaussians: Another View

- ▶ Which matrices are **valid** covariance matrices?
- ▶ 1. If  $C$  is the rotation of some diagonal covariance matrix  $C_0$ . That is,  $C = RC_0$
- ▶ 2. Equivalently,  $C$  is symmetric, positive semi-definite.

# Overview

- ▶ The probability density function for a multivariate Gaussian distribution is:

$$p(\vec{x}) = \frac{1}{(2\pi)^{d/2} |C|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(\vec{x} - \vec{\mu})^T C^{-1}(\vec{x} - \vec{\mu})\right)$$

- ▶ Here,  $C$  is the **covariance matrix**.

# Overview

- ▶ There are three cases, from least to most general:
  1.  $C$  is diagonal, with all the same entries.
    - ▶ **Spherical** Gaussians.
  2.  $C$  is diagonal, with different entries.
    - ▶ **Axis-Aligned** Gaussians.
  3.  $C$  is not diagonal.
    - ▶ **General** Gaussians.

# DSC 140A

*Probabilistic Modeling & Machine Learning*

Lecture 14 | Part 3

**Fitting Multivariate Gaussians**

# Fitting Multivariate Gaussians

- ▶ Suppose  $\vec{x}^{(1)}, \dots, \vec{x}^{(n)}$  came from a multivariate Gaussian.
- ▶ What were the parameters of that Gaussian?
- ▶ We can use the principle of **maximum likelihood**.

# What are the parameters?

$$p(\vec{x}) = \frac{1}{(2\pi)^{d/2} |\mathbf{C}|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(\vec{x} - \vec{\mu})^T \mathbf{C}^{-1}(\vec{x} - \vec{\mu})\right)$$

- ▶  $\vec{\mu}$ : controls Gaussian's location
- ▶  $\mathbf{C}$ : controls Gaussian's shape

# Estimating $\vec{\mu}$

- ▶ The maximum likelihood estimator for  $\mu$  is:

$$\vec{\mu}_{\text{MLE}} = \frac{1}{n} \sum_{i=1}^n \vec{X}^{(i)}$$

$$\vec{\mu}_{\text{MLE}} = \begin{pmatrix} \text{Avg. height} \\ \text{Avg. weight} \end{pmatrix}$$

# Estimating $C$

- ▶ First: make assumptions on covariance matrix.
- ▶ In order from strict to weak:
  - ▶ Spherical:  $C$  is diagonal, with all the same entries.
  - ▶ Axis-Aligned:  $C$  is diagonal, with different entries.
  - ▶ General:  $C$  is not diagonal.
- ▶ The weaker the assumptions, the more parameters to estimate.



# Fitting Spherical Gaussians

- ▶ Only one variance parameter:  $\sigma^2$ .
- ▶ The density function becomes:

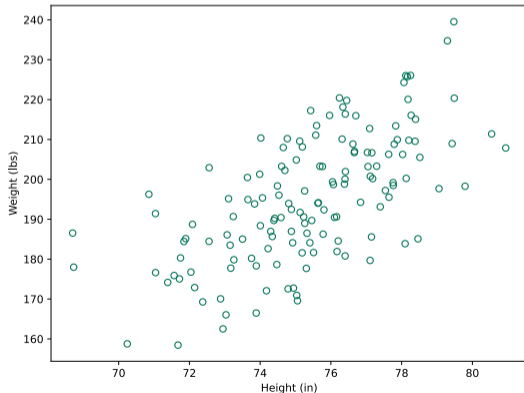
$$p(\vec{x}) = \frac{1}{(2\pi\sigma^2)^{d/2}} \exp\left(-\frac{(\vec{x} - \vec{\mu})^T(\vec{x} - \vec{\mu})}{2\sigma^2}\right)$$

- ▶ The maximum likelihood estimator:

$$\sigma_{\text{MLE}}^2 = \frac{1}{n} \sum_{i=1}^n \|\vec{x}^{(i)} - \vec{\mu}_{\text{MLE}}\|^2$$

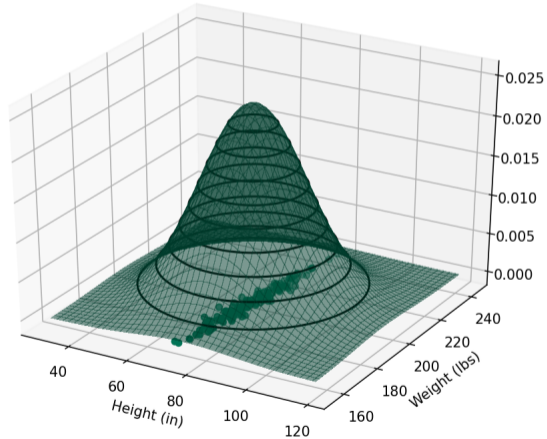
# Example: NBA Data

- ▶ What if we fit a spherical Gaussian to the NBA data?



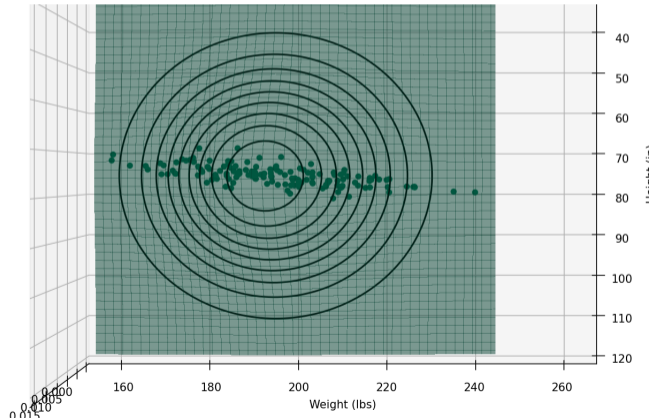
# Fitting Spherical Gaussians

Doesn't fit!



# Fitting Spherical Gaussians

Doesn't fit!



## Example: NBA Data

- ▶ Spherical Gaussians are not well-suited to this data.
- ▶ Perhaps if the data were **standardized...**
- ▶ Instead, try axis-aligned Gaussians.

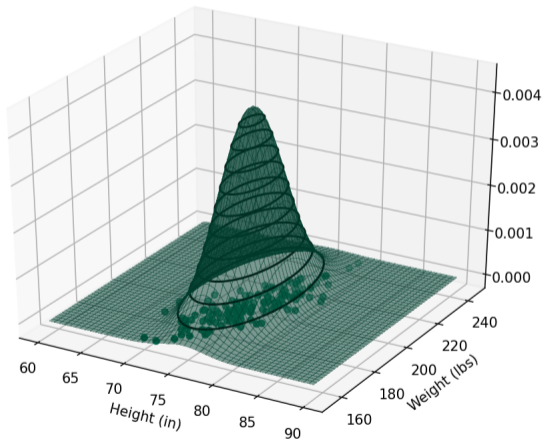
# Fitting Axis-Aligned Gaussians

- ▶ Variance for each axis:  $\sigma_1^2$  and  $\sigma_2^2$ .
- ▶ Maximum likelihood estimates:

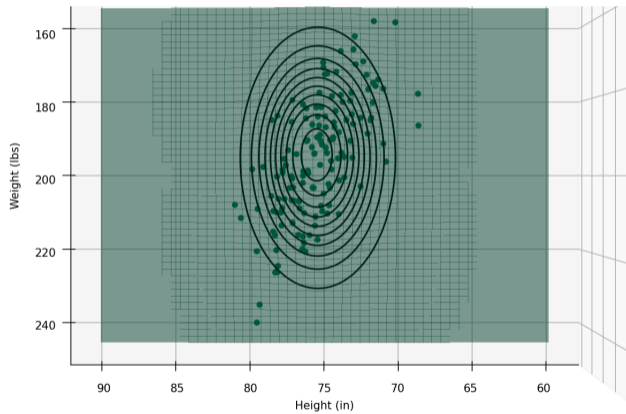
$\sigma_1^2$  = sample variance of heights

$\sigma_2^2$  = sample variance of weights

# Fitting Axis-Aligned Gaussians



# Fitting Axis-Aligned Gaussians





## Example: NBA Data

- ▶ Better, but still not great.
- ▶ Axis-aligned Gaussian does not capture correlation between height and weight.
- ▶ Try general Gaussian with full covariance.

# Fitting General Gaussians

- ▶ Must compute covariance for each pair of dimensions.
- ▶ Maximum likelihood estimate for covariance of feature  $i$  and  $j$ :

$$C_{ij} = \left( \frac{1}{n} \sum_{k=1}^n \vec{x}_i^{(k)} \vec{x}_j^{(k)} \right) - \mu_i \mu_j$$

# Computing the Covariance Matrix

Step 1. Make matrix with heights in first column, weights in second:

$$\begin{pmatrix} \text{height 1} & \text{weight 1} \\ \text{height 2} & \text{weight 2} \\ \dots & \dots \\ \text{height } n & \text{weight } n \end{pmatrix}$$

# Computing the Covariance Matrix

Step 2. Subtract sample mean height, mean weight from each column. Call this matrix  $X$ :

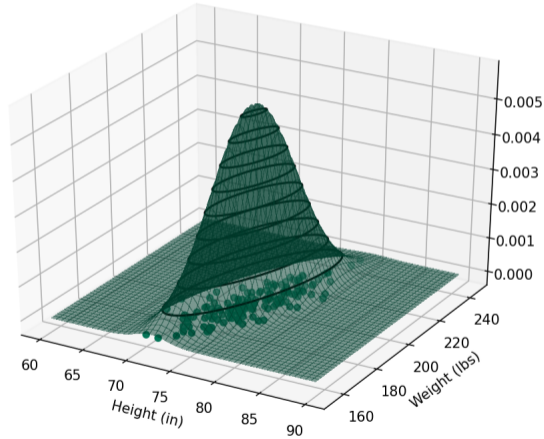
$$X = \begin{pmatrix} \text{height 1} - \text{mean height} & \text{weight 1} - \text{mean weight} \\ \text{height 2} - \text{mean height} & \text{weight 2} - \text{mean weight} \\ \dots & \dots \\ \text{height } n - \text{mean height} & \text{weight } n - \text{mean weight} \end{pmatrix}$$

# Computing the Covariance Matrix

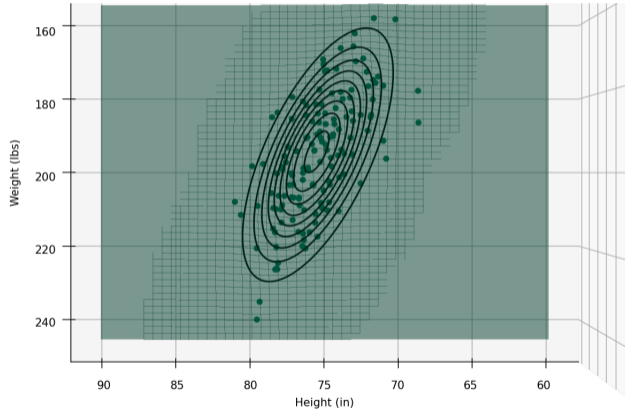
The empirical covariance matrix is then:

$$C = \frac{1}{n}X^T X$$

# Fitting General Gaussians



# Fitting General Gaussians



**Up next...**

Making predictions using these fitted Gaussians.



# DSC 140A

*Probabilistic Modeling & Machine Learning*

Lecture 14 | Part 4

**Discriminant Analysis**

# Bayes Classifier with MV Gaussians

1. Fit Gaussian for  $p(\vec{X} | Y = y)$  for each class,  $y$ .
2. For new point, predict  $y$  maximizing:

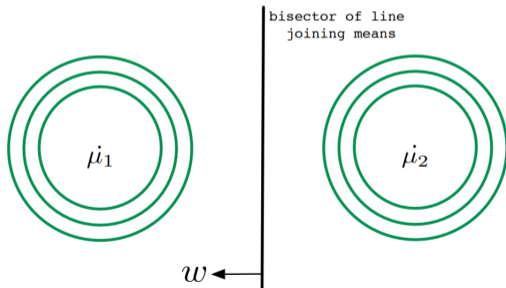
$$p(\vec{X} = \vec{x} | Y = y)\mathbb{P}(Y = y)$$

# Decision Boundary

- ▶ For every point in space, we have a classification.
- ▶ The **decision boundary**: surface between different classifications.
  - ▶ On one side, prediction is  $y_1$ ;
  - ▶ on the other, prediction is  $y_2$ .

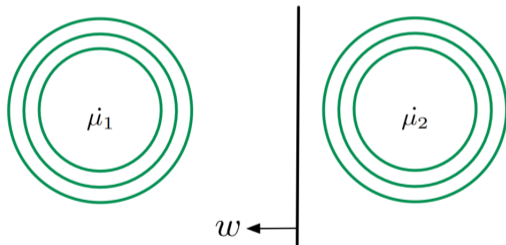
# Example #1

- ▶ Assume:
  - ▶ classes equally likely:  $\mathbb{P}(Y = 1) = \mathbb{P}(Y = 0)$
  - ▶ identical covariance matrices



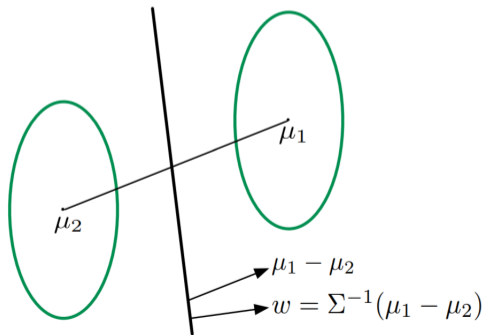
# Example #1

- ▶ If  $\mathbb{P}(Y = y_1) > \mathbb{P}(Y = y_2)$ :



# Example #2

- ▶ Assume:
  - ▶ covariance matrices identical, diagonal
  - ▶ that is: axis-aligned Gaussians



# Example

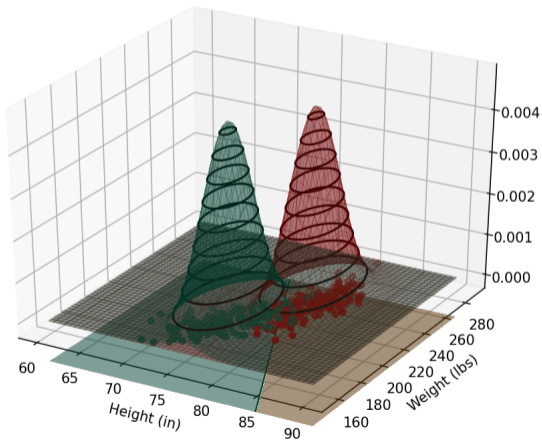
- ▶ Using identical Gaussians for each class, predict position given height and weight.
- ▶ How do we get one covariance matrix?
- ▶ **Don't** lump data together...
- ▶ Instead, compute covariance matrix for each class, perform weighted average:

$$C = \frac{n_1 C_1 + n_2 C_2}{n_1 + n_2}$$



C

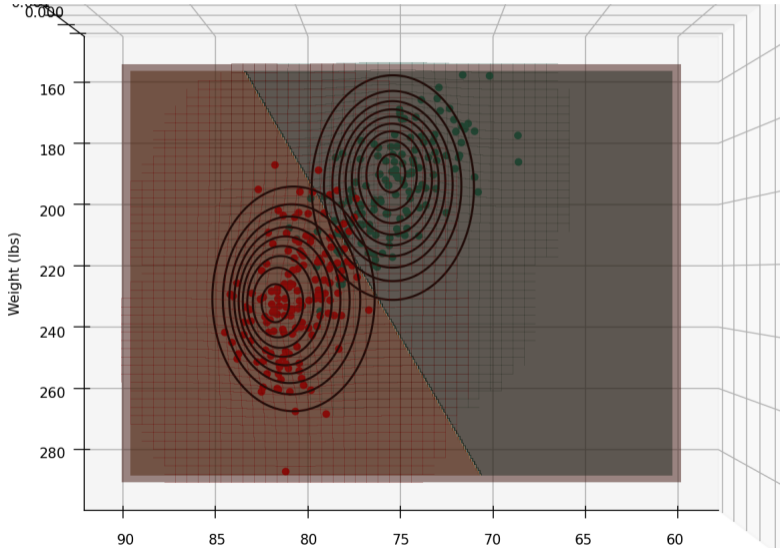
# Example





$$P(Y=1 | X=\vec{x})$$

# Example

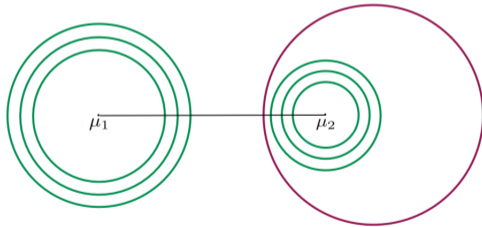


# Linear Discriminant Analysis

- ▶ When covariance matrices are **equal**, decision boundary is linear.
- ▶ This procedure is called **linear discriminant analysis** (LDA).
- ▶ True even if the Gaussians have full covariance.

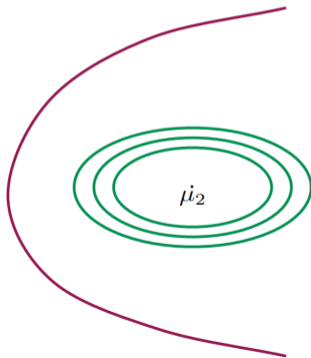
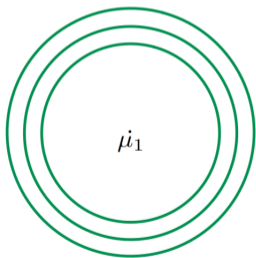
# Example #3

- ▶ Assume:
  - ▶ covariance matrices  $C_1, C_2$  different, non-diagonal

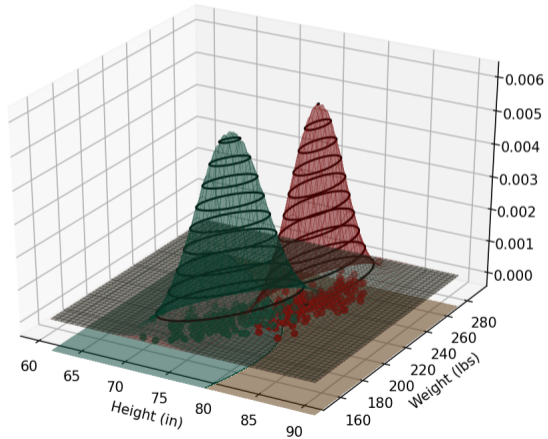


# Example #3

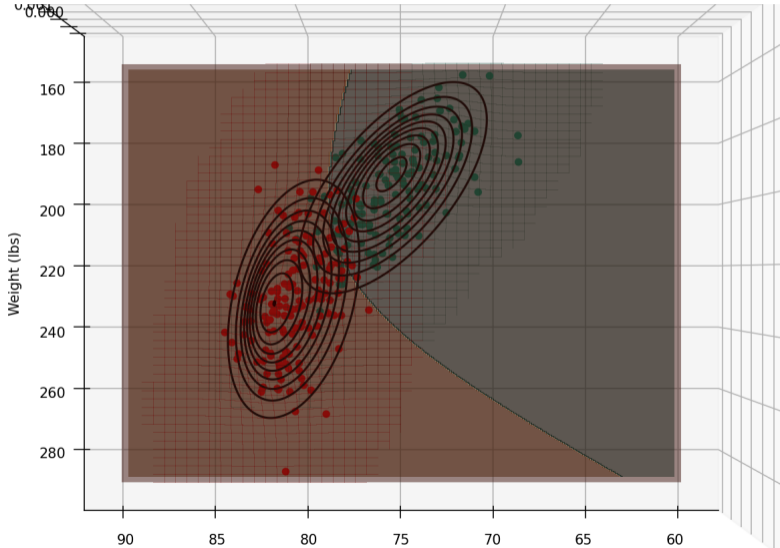
- ▶ Assume:
  - ▶ covariance matrices  $C_1, C_2$  different, non-diagonal



# Example



# Example

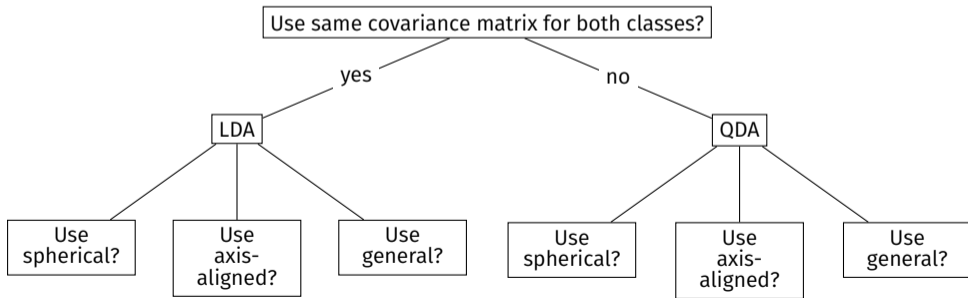


# Quadratic Discriminant Analysis

- ▶ When covariance matrices are **not** equal, decision boundary is quadratic (ellipsoidal, paraboloidal, hyperboloidal).
- ▶ This procedure is called **quadratic discriminant analysis** (QDA).

# LDA/QDA and Gaussian Type

- ▶ You can use any type of Gaussian within both LDA and QDA.





## In practice...

- ▶ A full covariance requires estimating  $\Theta(d^2)$  parameters; needs more data.
- ▶ Gaussian assumption may be a poor match for data.