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## DSC 140A - Midterm 01 Review

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### Problem 1.

Suppose  $f(\vec{x})$  is a **convex** function of  $\vec{x}$  and that the gradient of  $f$  at the point  $\vec{x}^{(1)} = (0, 5)^T$  is  $(-3, 5)^T$ .

Let  $\vec{x}^* = (x_1^*, x_2^*)$  be the minimizer of  $f$ ; you can assume that  $\vec{x}^* \neq \vec{x}^{(1)}$ , which implies that  $f(\vec{x}^*) < f(\vec{x}^{(1)})$ . True or False: it must be the case that  $x_2^* \geq 5$ .

**Solution:**

False as the gradient is the direction of maximal ascent. We would move in the direction of  $(3, -5)^T$  and therefore  $x_2^* \leq 5$ .

### Problem 2.

Recall that a subgradient of the absolute loss is:

$$\begin{cases} \text{Aug}(\vec{x}), & \text{if } \text{Aug}(\vec{x}) \cdot \vec{w} - y > 0, \\ -\text{Aug}(\vec{x}), & \text{if } \text{Aug}(\vec{x}) \cdot \vec{w} - y < 0, \\ \vec{0}, & \text{otherwise.} \end{cases}$$

Suppose you are running subgradient descent to minimize the risk with respect to the absolute loss in order to train a function  $H(x) = w_0 + w_1x_1 + w_2x_2$  on the following data set:

$x_1$	$x_2$	$y$
2	5	6
1	2	3

Suppose that the initial weight vector is  $\vec{w} = (0, 0, 0)^T$  and that the learning rate  $\eta = 1$ . What will be the weight vector after one iteration of subgradient descent?

**Solution:**

As  $\text{Aug}(\vec{x}) \cdot \vec{w} = 0$ ,  $\text{Aug}(\vec{x}) \cdot \vec{w} - y = -y < 0$ . So,  $\frac{\partial}{\partial \vec{w}} R(\vec{w}) = \frac{1}{n} \sum_{i=1}^n \frac{\partial}{\partial \vec{w}} L_{abs}$ . Plugging in our data we have,

$$\frac{\partial}{\partial \vec{w}} R(\vec{w}) = -\frac{1}{2} \left( \begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \right) = -\frac{1}{2} \begin{bmatrix} 2 \\ 3 \\ 7 \end{bmatrix} \text{ After 1 iteration of gradient descent } \vec{w} = (0, 0, 0)^T + \frac{1}{2}(2, 3, 7)^T = (1, 3/2, 7/2)^T.$$

### Problem 3.

Let  $X = \{\vec{x}^{(i)}, y_i\}$  be a data set of  $n$  points where each  $\vec{x}^{(i)} \in \mathbb{R}^d$ .

Let  $Z = \{\vec{z}^{(i)}, y_i\}$  be the data set obtained from the original by standardizing each feature. That is, if a matrix were created with the  $i$ -th row being  $\vec{z}^{(i)}$ , then the mean of each column would be 0, and the variance would be 1.

a) Suppose linear predictors  $H_1$  and  $H_2$  are fit on  $X$  and  $Z$  by minimizing the MSE, respectively.

True or False:  $H_1(\vec{x}^{(i)}) = H_2(\vec{z}^{(i)})$  for every  $i = 1, \dots, n$ .

**Solution:**

True. In linear functions, changing input unit do not change the output.

- b) Suppose that  $X$  and  $Z$  are both linearly-separable. Suppose Hard-SVMs  $H_1$  and  $H_2$  are trained on  $X$  and  $Z$ , respectively.

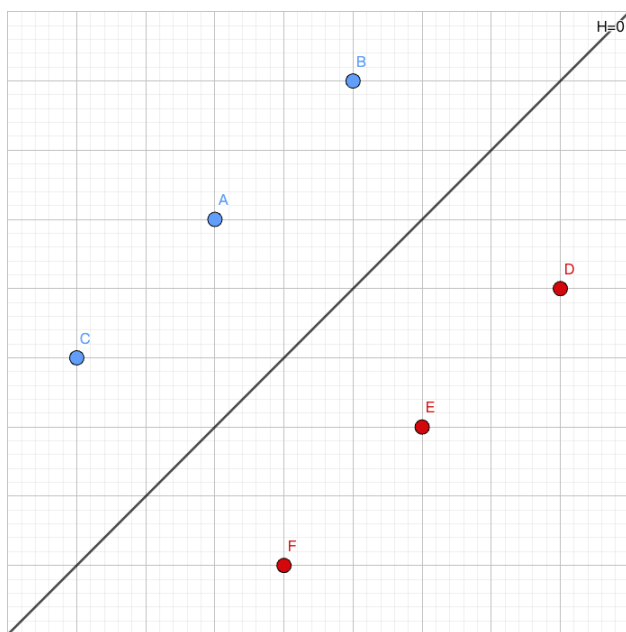
True or False:  $H_1(\vec{x}^{(i)}) = H_2(\vec{z}^{(i)})$  for every  $i = 1, \dots, n$ .

**Solution:**

False. In (Hard) SVMs, changing scales may change the output, e.g., by changing the set of support vectors.

**Problem 4.**

Consider the image below:



The blue points have label  $+1$ , and the red points have label  $-1$ . Suppose  $H$  is a linear prediction function, and when  $H$  is applied to the point  $A$  in the above image,  $H(\vec{x}) = 4$ . The black line in the middle of the image is the decision boundary  $H = 0$ .

You may assume that  $H$  is exactly in the middle of the points, and that all points are equidistant from the decision boundary.

- a) What is the mean square loss of this prediction function,  $H$ ?

**Solution:**

The output of  $H$  on the blue points is  $4$ , while for the red points it is  $-4$ . This follows from the fact that all points are equidistant from the decision boundary, and  $H$  is linear. The target label for the blue and red points is  $1$  and  $-1$ , respectively. So the prediction is off by  $3$  in each case. This makes the squared error on each point  $3^2 = 9$ , so the mean squared error (mean square loss) is  $9$ .

- b) True or false: there exists a linear prediction function  $H$  which has a mean square loss of zero on this data.

**Solution:**

True. One simple way is to modify  $H$ . Let  $H'(\vec{x}) = H(\vec{x})/4$ , then  $H'$  is also a linear prediction function with its output exactly correct for each data point.

Alternatively, here's a geometric argument: a linear prediction function in two dimensions fits a plane to the data, where we have lifted the blue points to a height of 1 and the red points to a height of -1. Because the points are all equidistant from the black line in the figure above, there is a way to draw a plane that goes exactly through all of the points.

**Problem 5.**

- a) True or false: Assume  $f(x) = f_1(x) + f_2(x) + \dots + f_k(x)$ . If  $f$  is convex, then all  $f_1, \dots, f_k$  are convex.

**Solution:**

False. (The inverse of the property that the sum of convex functions is also convex is false). Consider the counter-example where  $f(x) = 0$  and  $f_1(x) = -f_2(x)$ .

- b) True or false: Assume  $f(x) = g(h(x))$ . If  $f$  is convex, then both  $g$  and  $h$  are convex.

**Solution:**

False. (The inverse of the property that the composition of convex functions is also convex is false). Consider the counter-example where  $f(x) = x(x \geq 0)$  and  $g(x) = x^2, h(x) = \sqrt{x}$ , where  $h$  is non-convex.

- c) True or false: If  $f$  is convex, then  $-f$  is non-convex.

**Solution:**

False. Consider the counter-example  $f(x) = 0$ .

Note that: If  $f$  is convex, then  $-f$  is concave.